Attorney Docket No.: Q92363 Application No.: 10/572,956

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions and listings of claims in the application:

LISTING OF CLAIMS:

1. (currently amended): A computer-readable medium having embodied thereon a

computer program for a method of A device for detecting a road traveling lane, from images on a

road surface continuously picked up by image pickup means, the method comprising:

edge point detection means for detecting a plurality of edge points in a contour on the

image;

segment group producing means for producing a plurality of segment groups by

providing a line segment for the plurality of edge points-detected by said edge point detection

means, on the basis of continuity of distance and direction between neighboring edge points, and

grouping a plurality of line segments having a predetermined relationship with each other, to

produce each of the plurality of segment groups a segment group;

curve detection means for detecting a curve fitted to each of the plurality of segment

groupsthe segment group produced by said segment group producing means; and

lane boundary position defining means for comparing a plurality of curves distributed in

the vicinity of right and left lane boundaries out of the detected curves with the segment groups

detected by said curve detection means, with the segment groups produced by said segment

group producing means, to define a position of one curve as an innermost marking line, when a

segment group forming a curve closest to the center of said traveling lane has a predetermined

length and repeated cycle, and to define a position of a neighboring curve, outside of said

Attorney Docket No.: Q92363

Application No.: 10/572,956

innermost marking line relatively to the center of said traveling lane, as a position of a boundary

of said traveling lane.

2. (currently amended): The computer-readable medium A-device for detecting a road

traveling-lane as described in claim 1, wherein said-segment group producing means produces

one of said segment groups includes for a group including a predetermined line segment and

another line segment provided in an area of the predetermined distance and direction relative to

the predetermined line segments in said plurality of line segment.

3. (currently amended): The computer-readable medium A device for detecting a road

traveling lane as described in claim 1, wherein said segment group producing means provides

one of said line segments includes for a group of edge points including the plurality of edge

points detected by said edge point detection means, on the basis of continuity of distance and

direction between neighboring edge points.

4. (currently amended): The computer-readable medium A device for detecting a road

traveling lane as described in claim 1, wherein said segment group producing means determines

that there is wherein a predetermined relationship, to be processed as one group is determined,

when there is another line segment in an area of the predetermined distance and direction relative

to a predetermined line segment, in a group of line segments based on said plurality of line

segments.

Attorney Docket No.: Q92363

Application No.: 10/572,956

5. (currently amended): The computer-readable medium A-device for detecting a road

traveling lane as described in claim 1, wherein said curve detection means applies a curve-fitting

is applied to the grouped line segments, to detect said curve.

6. (currently amended): The computer-readable medium A device for detecting a road

traveling lane as described in claim 1, wherein, said lane boundary position defining means

determines-if said line segments have a predetermined length and cycle in a longitudinal

direction or a lateral direction to provide a block-like marking line, and removes-said block-like

marking line is removed from a lane boundary to be, when said lane boundary position defining

means determines affirmatively, and wherein said lane boundary position defining means

determines that the curve provided outside of said block-like marking line relatively to the center

of said traveling lane is <u>determined to be said</u> boundary of said traveling lane.

7. (currently amended): The computer-readable medium A device for detecting a road

traveling lane as described in claim 1, wherein said edge point detection means detects the

plurality of edge points on the image is detected picked up by said image pickup means, and

makes a reverse projection of coordinate data of the plurality of edge points is made on a 3-

dimensional road surface coordinate, to provide said plurality of edge points.

8. (currently amended): A computer-readable medium having embodied thereon a

computer program for a method of A device for detecting a road traveling lane, from images

continuously picked up on the road by image pickup means, the method comprising:

Attorney Docket No.: 092363

Application No.: 10/572,956

edge point detection means for detecting a plurality of edge points from a contour on the

images;

curve detection means for detecting curves fitted to the plurality of edge points detected

by said edge point detection means;

segment group producing means for grouping groups of edge points contributed to the

detected curves detected by said curve detection means, to produce segment groups; and

lane boundary position defining means for comparing a plurality of curves distributed in

the vicinity of right and left lane boundaries out of the detected curves with the segment groups

detected by said curve detection means, with the segment groups produced by said segment

group producing means, to define a position of one curve as an innermost marking line, when a

segment group produced for a curve closest to a center of said traveling lane indicates a

predetermined length and repeated cycle, and define a position of a neighboring curve outside of

said innermost marking line relatively to the center of said traveling lane, as a position of a

boundary of said traveling lane.

9. (currently amended): The computer-readable mediumA-device for detecting a road

traveling lane as described in claim 8, wherein said segment group producing means provides an

edge histogram is provided for the groups of edge points provided for the curves detected by said

curve detection means, and groups the groups of edge points contributed to peaks of said

histogram, to produce the segment groups.

Attorney Docket No.: Q92363 Application No.: 10/572,956

10. (currently amended): The computer-readable mediumA device for detecting a road

traveling lane as described in claim 9, wherein said lane boundary position defining means

determines if the peaks of said histogram have a predetermined length and cycle in a longitudinal

direction or a lateral direction to provide a block-like marking line, and removes-said block-like

marking line is removed from a lane boundary to be, when said lane boundary position defining

means determines affirmatively, and wherein said lane boundary position defining means

determines that the curve provided outside of said block-like marking line relatively to the center

of said traveling lane is <u>determined to be said</u> boundary of said traveling lane.

11. (currently amended): The computer-readable medium A device for detecting a road

traveling lane as described in claim 8, wherein said edge point detection means detects the

plurality of edge points is detected on the image picked up by said image pickup means, and

makes-a reverse projection of coordinate data of the plurality of edge points is made on a 3-

dimensional road surface coordinate, to provide said plurality of edge points.